

PROXIMAL-POINT LIKE ALGORITHMS FOR ABSTRACT CONVEX MINIMISATION PROBLEMS

R. Díaz Millán J. Ugon

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INTRODUCTION

$$x_{k+1} = x_k - \alpha_k \nabla f(x_k)$$

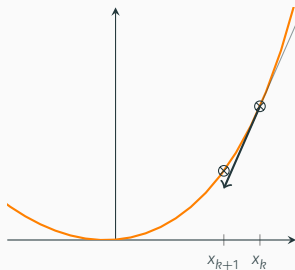
$$x_{k+1} = x_k - \alpha_k \nabla f(x_k)$$

We want to generalise this method to *globally* minimise some classes of *nonconvex* functions.

THE SUBGRADIENT METHOD

Let f be convex. The (sub)gradient method step is:

$$x_{k+1} = x_k - \alpha_k \nabla f(x_k)$$

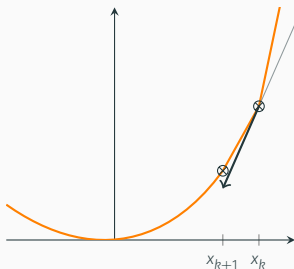


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where $g_k \in \partial f(x_k)$.

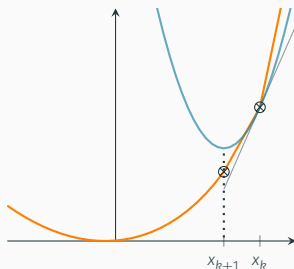


THE SUBGRADIENT METHOD

Let f be convex. The (sub)gradient method step is:

$$\begin{aligned}x_{k+1} &= x_k - \alpha_k g_k \\ &= \operatorname{argmin} \left(\langle g_k, x \rangle + \frac{1}{2c_k} \|x - x_k\|^2 \right)\end{aligned}$$

where $g_k \in \partial f(x_k)$.



The subgradient method is a linearisation of the proximal point method:

$$x_{k+1} = \text{prox}_{c_k, f}(x_k)$$

$$\text{where } \text{prox}_{c_k, f}(x_k) = \underset{x \in X}{\operatorname{argmin}} f(x) + \frac{1}{2c_k} \|x - x_k\|^2$$

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BREGMAN-BASED METHODS

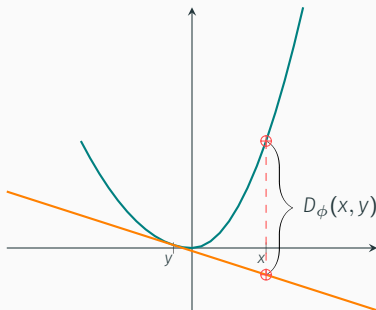
BREGMAN DIVERGENCE

Let ϕ be a continuously differentiable strongly convex function.

Definition (Bregman Divergence (Brègman 1965))

The *Bregman divergence* is the function

$$D_{\phi}(x, y) = \phi(x) - \phi(y) - \langle \nabla \phi(y), x - y \rangle.$$



BREGMAN PROXIMAL POINT METHOD (BREGMAN 1967)

$$x_{k+1} = \operatorname{argmin}_{x \in X} f(x) + \frac{1}{c_k} D_\phi(x, x_k)$$

$$u_k \in \partial f(x_k)$$

$$x_{k+1} = \operatorname{argmin}_{x \in X} \langle u_k, x \rangle + \frac{1}{c_k} D_\phi(x, x_k),$$

GENERALISED BREGMAN DIVERGENCE

Let ϕ be a **strongly convex function**.

Definition (Generalised Bregman Divergence (Kiwiel 1997a))

The *generalised Bregman divergence* is a function

$$D_{\phi}^{\lambda}(x, y) = \phi(x) - \phi(y) - \langle \lambda, x - y \rangle.$$

where $\lambda \in \partial\phi(y)$.

$D_{\phi}^{\lambda}(x, y) \geq 0$ for any x, y with equality iff $x = y$.

GENERALISED BREGMAN PROXIMAL POINT METHOD (KIWIEL 1997B)

$$\begin{cases} x_{k+1} = \operatorname{argmin}_{x \in X} f(x) + \frac{1}{c_k} D_{\phi}^{\lambda_k}(x, x_k) \\ \lambda_{k+1} = c_k u_k - \lambda_k, \end{cases} \quad \text{where } u_k \in \partial f(x_k).$$

$$\begin{cases} u_k \in \partial f(x_k) \\ x_{k+1} = \operatorname{argmin}_{x \in X} \langle u_k, x \rangle + \frac{1}{c_k} D_{\phi}^{\lambda_k}(x, x_k), \\ \lambda_{k+1} = c_k u_k - \lambda_k \end{cases}$$

ASSUMPTIONS FOR CONVERGENCE OF MIRROR DESCENT

- ϕ strongly convex:

$$\phi(y) \geq \phi(x) + \langle u, x \rangle + \sigma \|y - x\|^2, \forall x, y \in X, u \in \partial\phi(x)$$

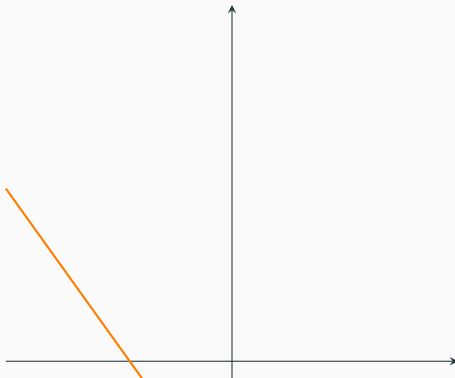
- f convex and continuous.
- $\|u\|_*$ bounded for all $u \in \partial f(x), x \in X$.

ABSTRACT CONVEXITY

CONVEXITY

A lower semi-continuous convex function can be written as a supremum of affine functions:

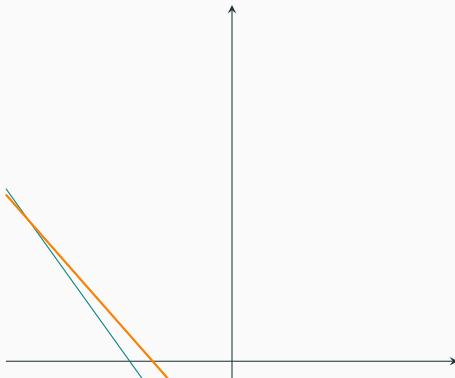
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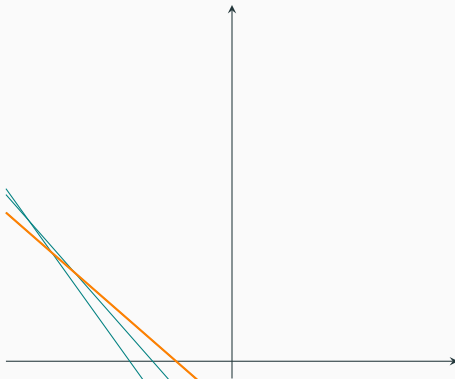
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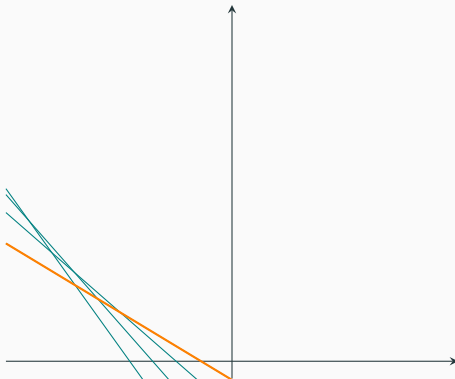
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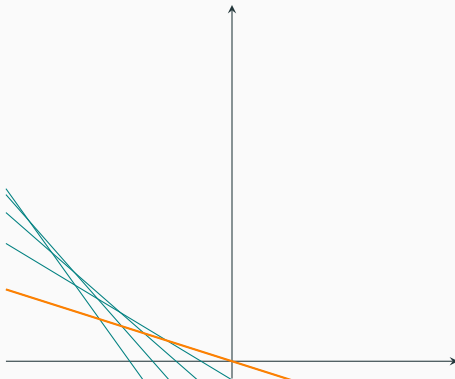
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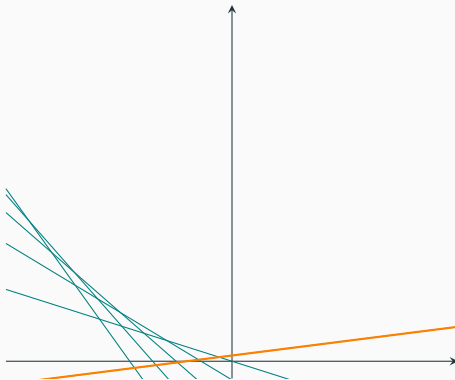
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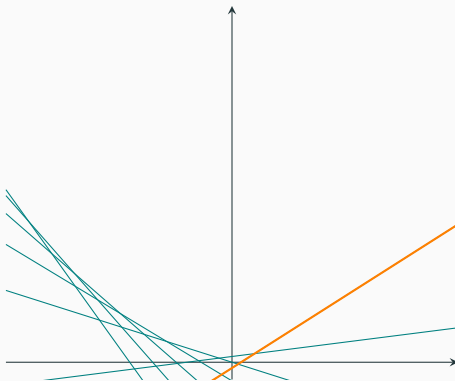
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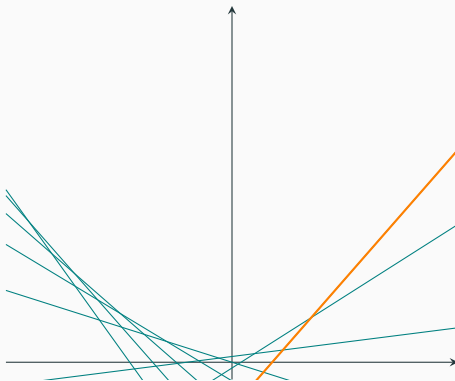
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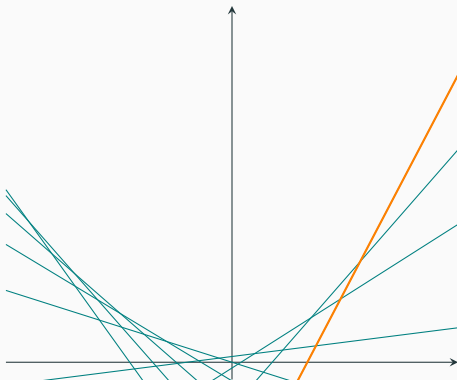
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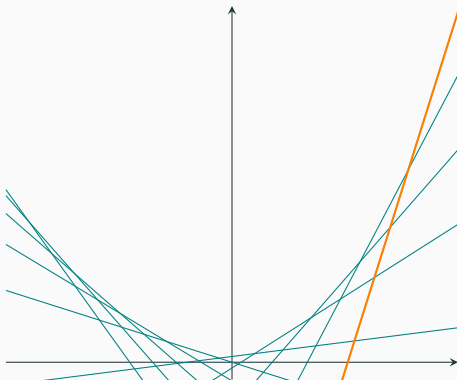
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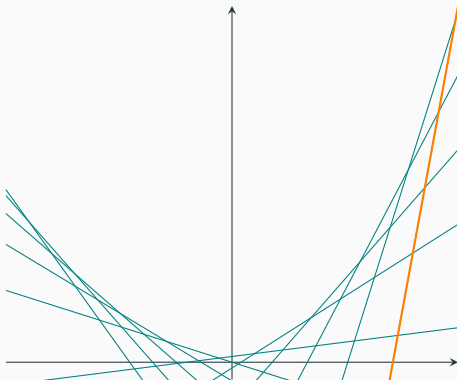
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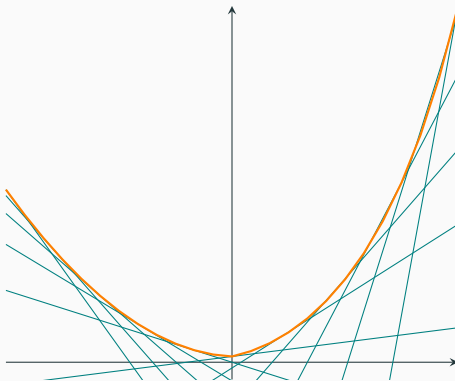
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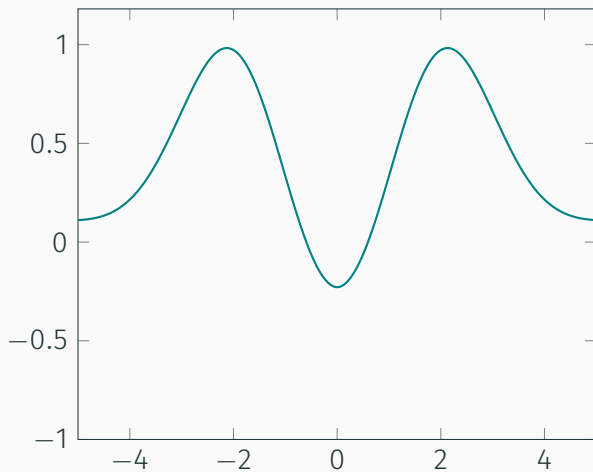
Definition (abstract convex function (Kutateladze and Rubinov 1972, 1976))

Let L be a family of functions defined on X . The function $f : X \rightarrow \mathbb{R}$ is called (L, X) -convex if there exists $U \subset L$ such that

$$f(x) := \sup_{u \in U} u(x)$$

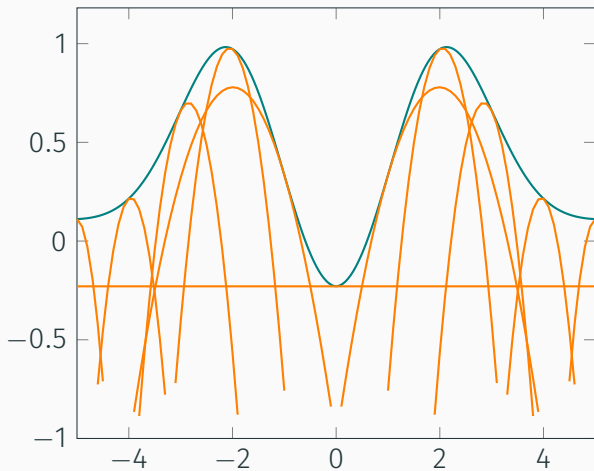
ABSTRACT CONVEX FUNCTION: EXAMPLE

$$L = \{ax^2 + bx : a, b \in \mathbb{R}\}$$



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Let L be a family of functions and f a (L, X) -convex function.

Definition (Abstract Subdifferential (Rubinov 2000))

$$\partial_L f(x) = \{u \in L : f(y) \geq f(x) + u(y) - u(x), \forall y \in X\}$$

1. Cutting Angle Method (Andramonov, Rubinov, and Glover 1999): Lipschitz continuous functions.
2. Proximal Point Method (Bednarczuk, Lorenz, and Tran 2025): Weakly convex functions.

ABSTRACT BREGMAN PROXIMAL METHODS

Definition (Abstract Bregman Divergence (Grasmair 2010))

Let ϕ be a (L, X) -function and $y \in X$, and let $\lambda \in \partial_L \phi(y)$. The L -Bregman divergence from y with respect to λ as

$$D_{\phi}^{\lambda}(x, y) = \phi(x) - \phi(y) - (\lambda(x) - \lambda(y))$$

ABSTRACT BREGMAN PROXIMAL POINT METHOD (DÍAZ MILLÁN AND U. 2025)

$$\begin{cases} x_{k+1} \in \underset{x \in X}{\operatorname{Argmin}} f(x) + \frac{1}{c_k} D_{\phi}^{\lambda_k}(x, x_k) \\ \lambda_{k+1} = c_k u_k - \lambda_k, \end{cases} \quad \text{where } u_k \in \partial_{\textcolor{brown}{L}} f(x_k).$$

ASSUMPTIONS

1. L is a linear space.
2. Sum Rule: $\partial_L \phi(x) + \partial_L f(x) = \partial_L(\phi + f)(x)$.
3. $\sum_{k=1}^{\infty} c_k = \infty$.

Let ϕ and f be L -convex functions. We want to minimise $f(x)$.

$$\begin{cases} u_k \in \partial_{\textcolor{brown}{L}} f(x_k) \\ x_{k+1} \in \underset{x \in X}{\text{Argmin}} u_k(x) + \frac{1}{c_k} D_{\phi}^{\lambda_k}(x, x_k), \\ \lambda_{k+1} = c_k u_k - \lambda_k \end{cases}$$

ASSUMPTIONS

1. $L - L = L$.
2. $u(x) - u(y) \leq D_\phi^\lambda(x, y) + \phi^*(u)$.
Classical case: $\langle u, x - y \rangle \leq 1/2 \|x - y\|^2 + 1/2 \|u\|_*^2$.
3. $\exists \alpha > 1 : \phi(cu) \leq c^\alpha \phi^*(u)$ for any $c \geq 0$.
Classical case: ϕ is strongly convex implies $\alpha = 2$.
4. $\phi^*(u)$ bounded for any $u \in \partial_L f(x)$, any $x \in X$.
Classical case: $1/2 \|u\|_*^2$ is bounded.
5. $\sum_{i=1}^{\infty} c_k = \infty$ and $\sum_{i=1}^{\infty} c_k^\alpha < \infty$.
6. Very minimal assumption on L .

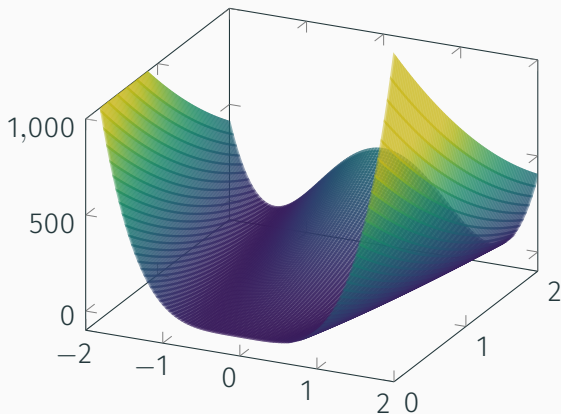
NUMERICAL EXPERIMENTS

ROSENBROCK FUNCTION

$$L = \{a\|x\|^2 + \langle b, x \rangle : (a, b) \in \mathbb{R} \times \mathbb{R}^n\}$$

$$\phi(x) = \|x\|^3$$

$$f(x) = (1 - x)^2 + a(y - x^2)^2, a = 100.$$

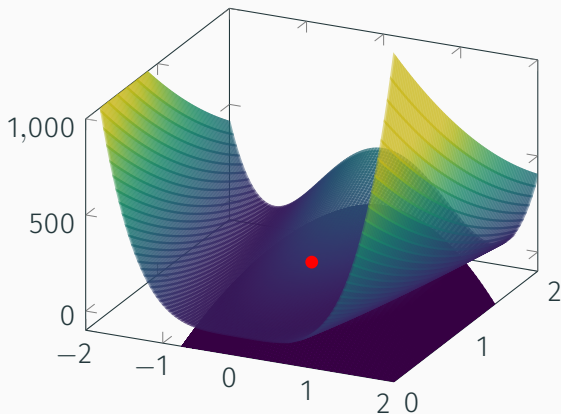


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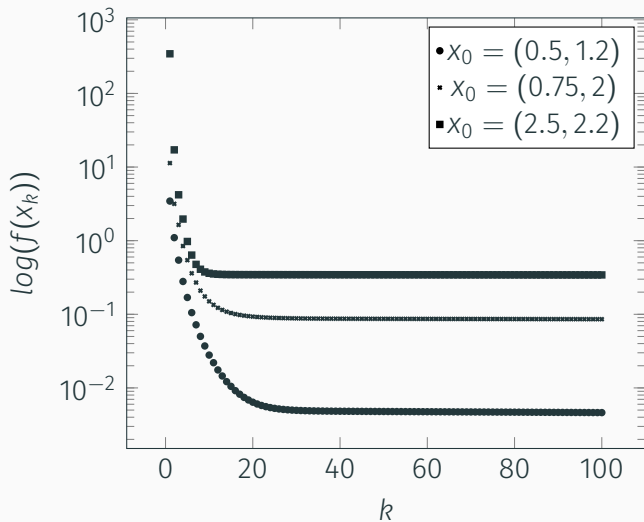
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ITERATIONS



EXAMPLE (BUI ET AL. 2021)

Let $L = \{ax^2 + b : a, b \in \mathbb{R}\}$ and let $f(x) = f_1(x) + f_2(x) + f_3(x)$ where

$$f_1(x) = x^4 - x^2$$

$$f_2(x) = 1 - 2|x|$$

$$f_3(x) = \begin{cases} 1 - 2|x| & \text{if } -\frac{1}{2} \leq x \leq \frac{1}{2}, \\ 0 & \text{otherwise.} \end{cases}$$

$$\phi(x) = -|x|.$$

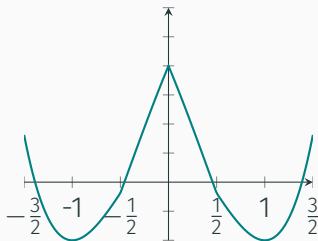
The Bregman divergence is then:

$$D_{\phi}^{\lambda}(x, y) = -|x| + |y| + \frac{x^2 - y^2}{2|y|}$$

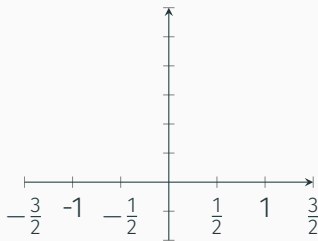
- Well defined for any x and any $y \neq 0$.
- $D_{\phi}^{\lambda}(x, y) = D_{\phi}^{\lambda}(x, -y)$ for any x and $y \neq 0$.

NUMERICAL EXPERIMENTS

$$f(x) + D_{\phi}^{\lambda}(x, x_k)$$

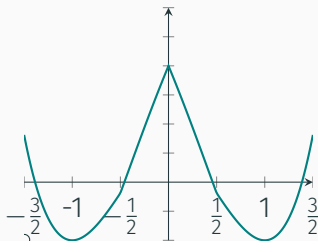


$$D_{\phi}^{\lambda}(x, x_k)$$

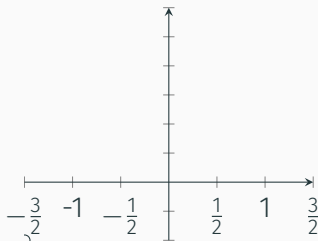


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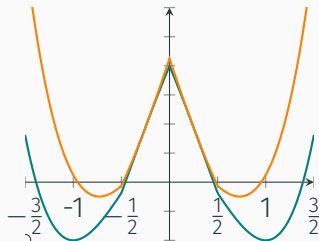


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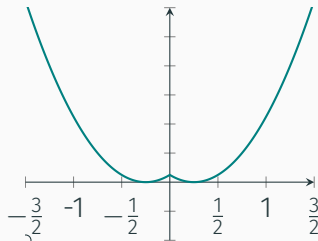


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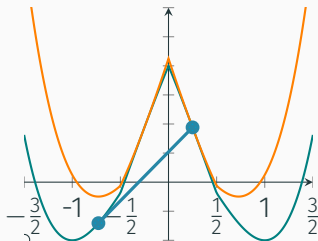


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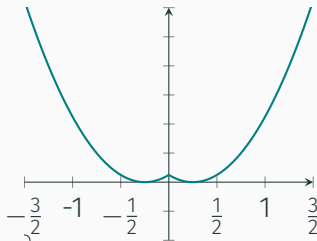


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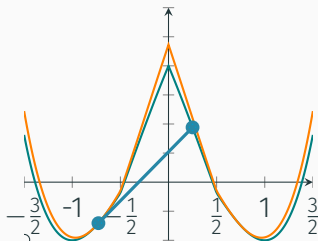


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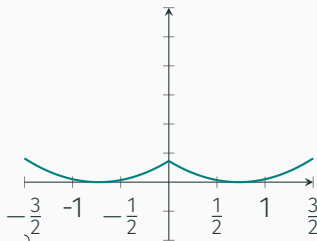


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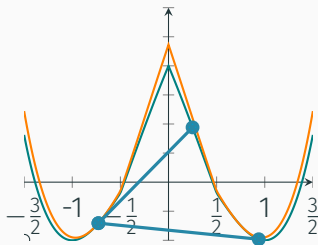


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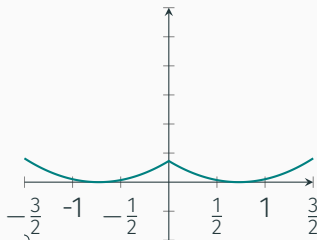


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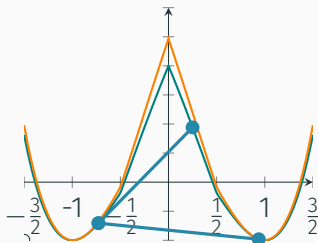


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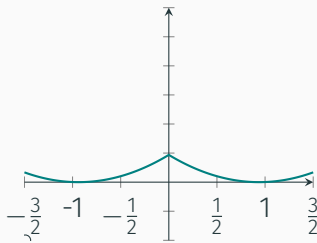


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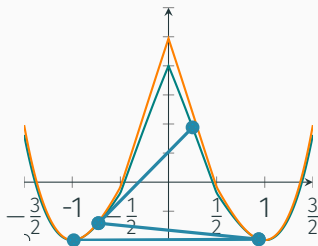


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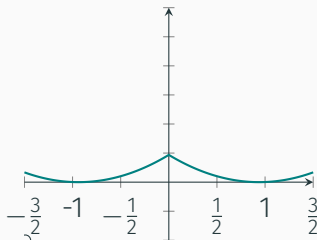


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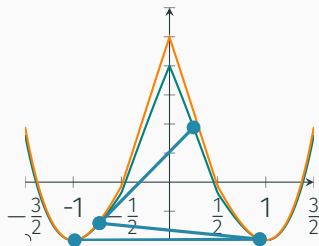


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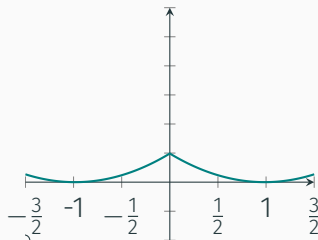


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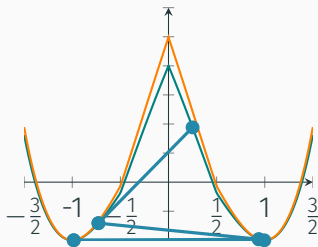


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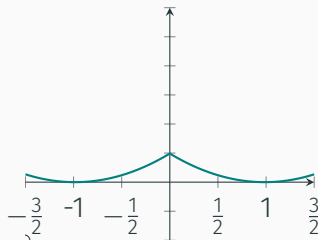


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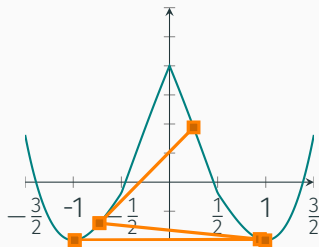


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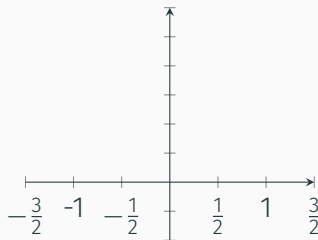


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REFERENCES

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